

OVERVIEW

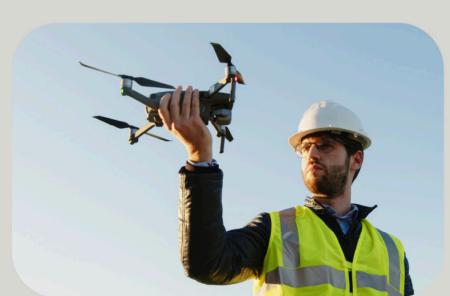
TYPOGRAPHY & FONTS

LOGO & APPLICATIONS

MARITIME SURVEILLANCE

BRAND ASSETS

COLOR PALETTE MOCKUPS IMAGERY





_lmagery **CHARISMA**







OBJECTIVE 1

OBJECTIVE 2

CHARSMA, aims to device next-generation Maritime Surveillance technology leveraging on heterogeneous autonomous robotic architectures, including unmanned serial, see surface and underwater vehicles. Rey to this innovation is devising both handware and software that can be attached as an add-on to existing fleets of Unmanned Vehicles (UVs). The addin will enable UVs to collectively form a mesh network for communication at the low-er-level, on top of which a Distributed Shared Memory (DSM) service will be deployed. The DSM will act as the connective tissue for decentralized data exchange that will be critical for devising advanced swarming algorithms to conduct Markime Surveillance. These swarming behaviour will be largely based on data fusion Machine Learning models. To monitor and control these capability-augmented UV swarms, a Maritime Surveillance Digital Twin will also be implemented.

By combining the expertise, intellectual property and Proof of Concepts in distributed applications (Algohylis Ltd), marisime research and robotics (CMM), and digital turins and machine learning (CYENS), we will develop a next generation framework for Muritime Surveillance, that will ensure reflable, robust and dependable data collection, provide a comprehensive digital representation of critical situations for better assessment, and will support decision making and high-level control of UV Sweams by competent operators. The entire framework will be valided and demonstrated in a relevant environment (TRL). Specifically, the addon device will be deployed over a set of heterogeneous UVs with advanced sweaming behaviours capable of specifically monitoring maritime infrastructure.





OVERVIEW



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These swarming behaviours will be largely based on data fusion Machine Learning models. To monitor and control these capability-augmented UV swarms, a Maritime Surveillance Digital Twin will also be implemented.

By combining the expertise, intellectual property and Proof of Concepts in distributed applications (Algolysis Ltd), maritime research and robotics (CMMI), and digital twins and machine learning (CYENS), we will develop a next generation framework for Maritime Surveillance, that will ensure reliable, robust and dependable data collection, provide a comprehensive digital representation of critical situations for better assessment, and will support decision making and high-level control of UV Swarms by competent operators. The entire framework will be validated and demonstrated in a relevant environment (TRL6). Specifically, the addon device will be deployed over a set of heterogeneous UVs with advanced swarming behaviours capable of specifically monitoring maritime infrastructure (e.g. aquaculture facilities).













Primary

Secondary

Extended













Symbol

App icon





Social icon





CHARISMA

Signate Grotesk	min 48pt	Headings & Subheadings		
		H1	H2	H3
'The five boxing wizards jump quickly."	_Black	72 pt	60pt	48pt
Noka	min 18pt	Subheadings		
		H3	нч	Н5
"The five boxing wizards jump quickly."	_Medium	48pt	36pt	18pt
"The five boxing wizards jump quickly."	_Semibold	48pt	36pt	18pt
Manrope	min 9pt	Running Text		
'The five boxing wizards jump quickly."	_Medium			



HEX	#1A1F16	#2B5B38	#0D32A0	#94ECBE	#E5E4E0	#E3E9DA
CMYK	16,0,29,88	53,0,38,64	92,69,0,37	37,0,19,7	0,0,2,10	3,0,6,9
RGB	R=26	R=43	R=13	R=133	R=217	R=221
	G=31	G=91	G=50	G=221	G=216	G=227
	B=22	B=56	B=145	B=175	B=212	B=212