

Tracing the Latencies of Ares: A DSM Case Study



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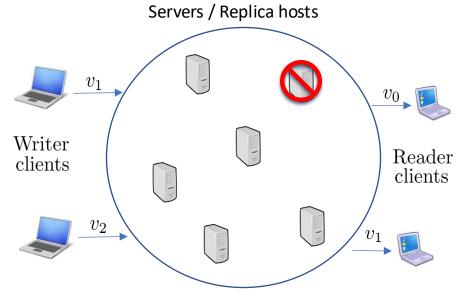








Distributed Shared Memory Emulations (DSMs)



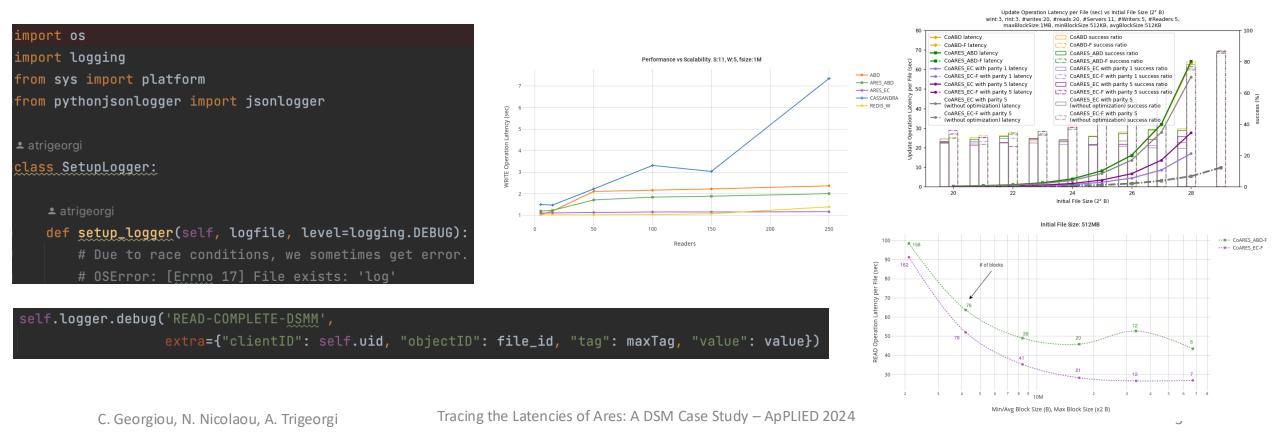
Shared read/write object

- A set of servers (configuration) maintain replicas of the same data object.
- Clients (readers/writers) access the object by sending messages to these servers.
- Read/Write operations are structured in terms of phases.
- Each phase consists of two communication exchanges (broadcast & convergecast).
- Fixed Configuration -> Static environment, Reconfiguration -> Dynamic environment
- Consistency guarantees
 - Safety, Regularity, Atomicity (Atomic DSMs) [Lamport 1986]

L. Lamport, "On Interprocess Communication," Distributed Computing, vol. 1, no. 2, pp. 77–101, 1986.

Performance Analysis Challenges in DSMs

- Identifying performance bottlenecks in complex DSMs can be challenging
- Traditional logging techniques may not provide sufficient insight



"Distributing Tracing is a monitoring technique used to track individual requests as they move across multiple components within a distributed system. It helps to pinpoint where failures occur and what causes poor performance."

Distributed Tracing – Terminology

- A trace represents the entire journey of a request.
- A **span** represents a unit of work within a trace (e.g., procedures, sections of code).
- Tracings tools: Opentemetry, Zipkin, Jaeger.

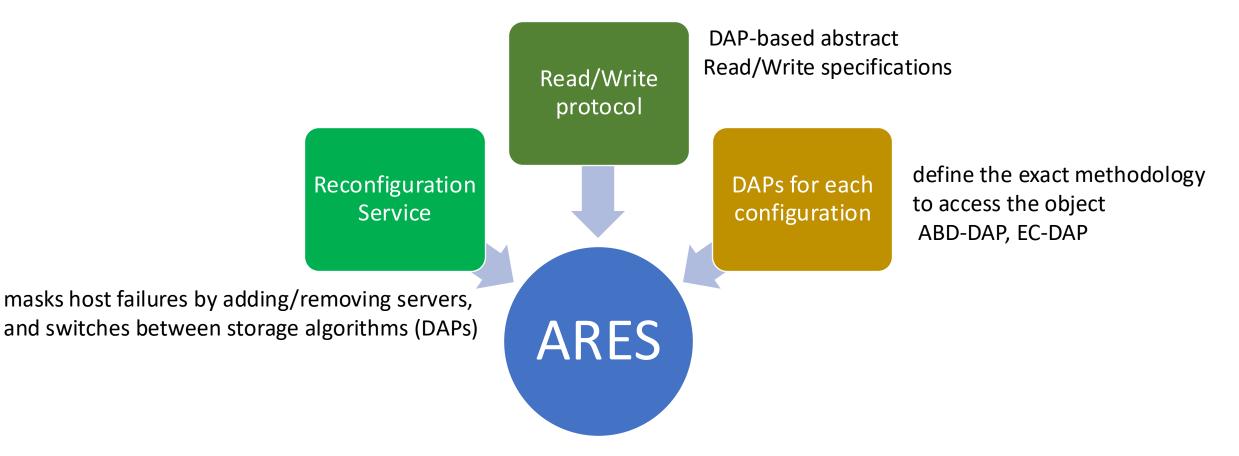


Spans

Main Objective

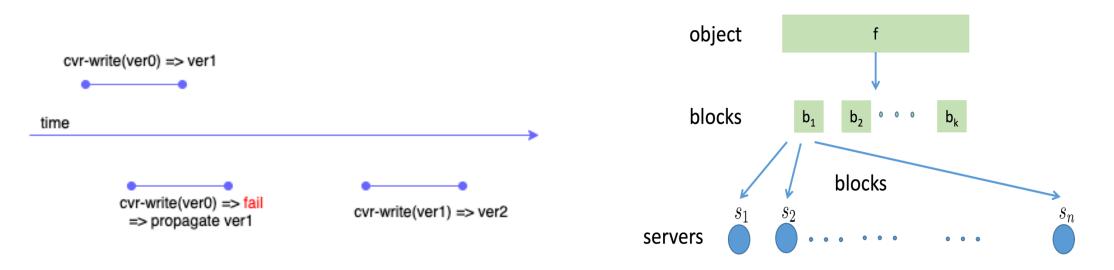
Our main objective is to bring Distributed Tracing into DSMs. We will achive this through the **ARES** DSM.

ARES - Adaptive, Reconfigurable, Erasure Code, Atomic Storage

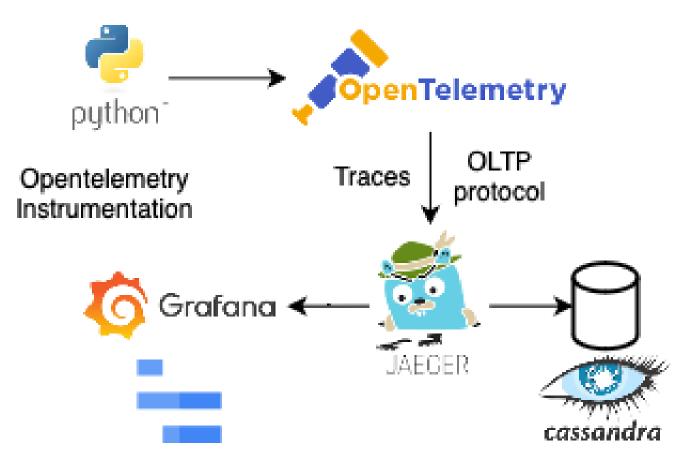


Evaluated Algorithms

ARESABD	This is Ares that uses the ABD-DAP implementation.
CoARESABD	The coverable version of ARESABD.
CoARESABDF	The fragmented version of CoARESABD.
ARESEC	This is ARES that uses the EC-DAP implementation.
CoARESEC	The coverable version of ARESEC.
CoARESECF	This is the two-level data striping algorithm obtained when <i>CoARESF</i> is used with the EC-DAP implementation; i.e., it is the fragmented version of <i>CoARESEC</i> .



Methodology: ARES Distributed Tracing



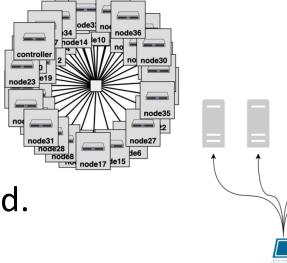
Experimental Setup

We used two main tools to run the experiments:

- Emulab: an emulated WAN environment testbed.
 - 39 machines with 100 Mb/s bandwidth
 - Each server is deployed on a different machine.
 - Clients are all deployed in the remaining machines in a round robin fashion.
- Ansible: a tool to automate different IT tasks.

• Performance Metric

- Operation latency of clients (Communication + Computation Overhead).
- Sample traces near the average duration for each scenario.
- Three executions.



Control machine

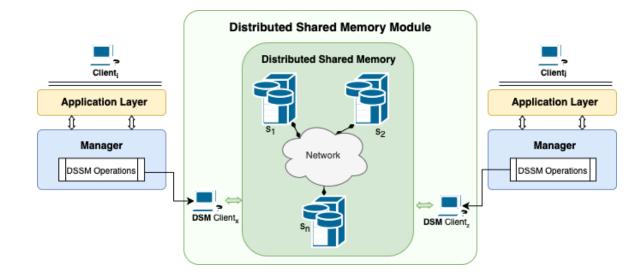
Ansible

Playbook

Debug Levels

Monitor read, write, and reconfig operations at two debug levels:

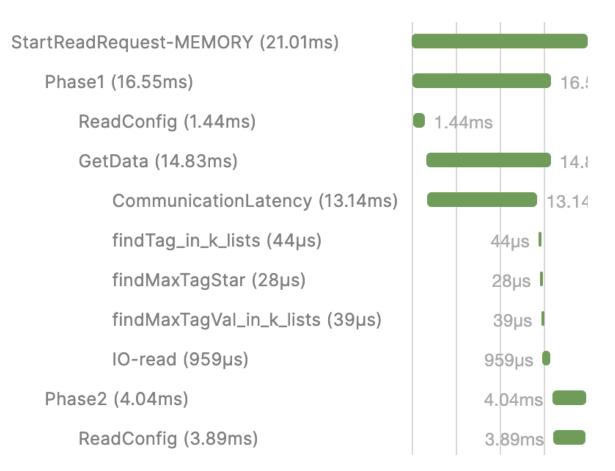
- User: This level includes the computation latency and the latencies for exchaning requests with the DSMM.
- **Memory:** This level includes communication and computation latencies within the DSMM.



File Size

StartReadRequest-MEMORY (1m 40s) Phase1 (1m 19s) ReadConfig (1.87ms) 1.87ms GetData (1m 19s) CommunicationLatency (1m 13s) findTag_in_k_lists (66µs) 66µs findMaxTagStar (20µs) 20µs | findMaxTagVal_in_k_lists (5.87s) 5.87s 🛢 DecodeLatency (5.84s) 5.84s 🌒 Phase2 (21.42s) 21.42s PutData (21.28s) 21.28s EncodeLatency (10.21s) 10.21s CommunicationLatency (11.07s) ReadConfig (2.72ms)

ARESEC, S:11, W:5, R:5, fsize:512MB, Debug Level:DSMM



CoARESECF, S:11, W:5, R:5, init fsize:512MB, Debug Level:DSMM

-LUDED

1m

1m

1m '

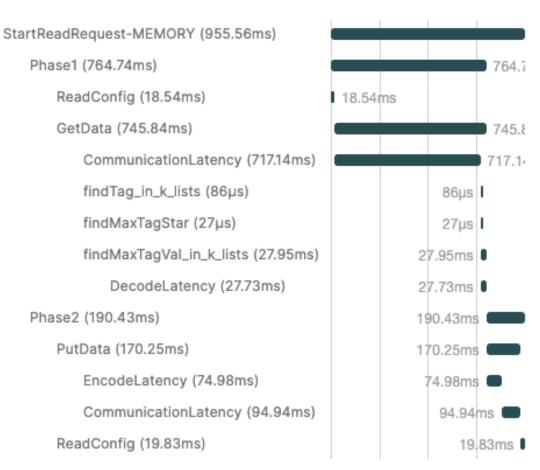
11.07s 🔲

2.72ms

Participation Scalability

StartReadRequest-MEMORY (3.77s) Phase1 (3.56s) ReadConfig (23.78ms) 23.78ms GetData (3.53s) CommunicationLatency (3.53s) findTag_in_k_lists (65µs) findMaxTagStar (30µs) findMaxTagVal_in_k_lists (7.47ms) DecodeLatency (7.3ms) Phase2 (212.79ms) PutData (187.03ms) EncodeLatency (7.42ms) CommunicationLatency (179.31ms) ReadConfig (25.45ms)

ARESEC, S:3, W:5, R:50, fsize:4MB, Debug Level:DSMM



ARESEC, S:11, W:5, R:50, fsize:4MB, Debug Level:DSMM

65µs

30µs |

7.47ms

7.3ms

212.79ms

187.03ms

7.42ms

179.31ms

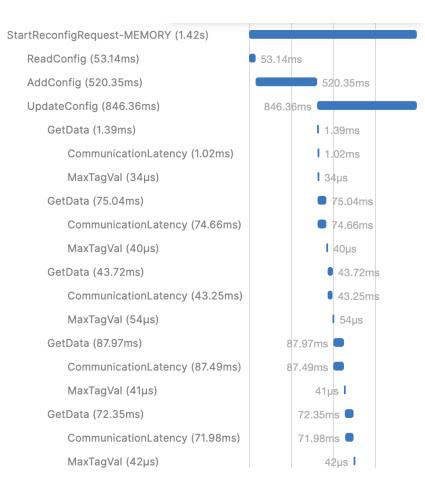
25.45ms

Longevity

StartReadRequest-MEMORY (568.45ms) Phase1 (402.5ms) ReadConfig (160.35ms) GetData (14.03ms) CommunicationLatency (10.52ms) findTag_in_k_lists (33µs) findMaxTagStar (21µs) findMaxTagVal_in_k_lists (30µs) GetData (64.99ms) CommunicationLatency (64.54ms) MaxTagVal (80µs) GetData (56.03ms) CommunicationLatency (55.65ms) MaxTagVal (37µs) GetData (44.04ms) CommunicationLatency (43.73ms) MaxTagVal (35µs) GetData (61.55ms) CommunicationLatency (61.16ms) MaxTagVal (47µs) Phase2 (165.58ms) PutData (65.66ms) CommunicationLatency (65.52ms) ReadConfig (97.06ms)

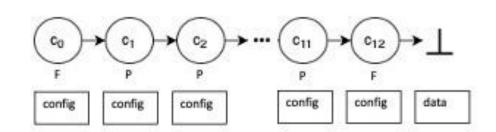


CoAresF, S:11, W:5, R:15, G=5, fsize:4MB, Debug Level:DSMM



CoAresF, S:11, W:5, R:15, G=5, fsize:4MB, Debug Level:DSMM

The Latencies of **read-config** and **get-data**.



StartReconfigRequest-MEMORY (1.01s) ReadConfig (55.85ms) 55.85ms AddConfig (321.38ms) 321.38ms UpdateConfig (625.26ms) 625.26ms Phase1 (551.1ms) 551.1ms GetData (38.59ms) 38.59ms GetData (28.12ms) GetData (39.03ms) 39.03ms 🛢 GetData (39.41ms) 39.41ms GetData (39.71ms) 39.71ms GetData (32.78ms) 32.78ms GetData (40.4ms) 40.4ms 🛢 GetData (32.21ms) 32.21ms GetData (40.22ms) GetData (32.22ms) GetData (33.54ms) GetData (32.29ms) GetData (2.34ms) Phase2 (52.12ms) PutData (47.57ms) FinalizeConfig (1.71ms)

28.12ms

40.22ms

32.22ms

33.54ms

32.29ms 🛙

2.34ms

52.12ms

47.57ms

1.71ms

Conclusions

Distributed tracing is crucial for diagnosing and resolving performance issues in DSM algorithms.

Optimization Strategies

- **Piggy-backing**: Integrating configurations with read/write messages to expedite configuration discovery.
- Garbage Collection: Eliminating obsolete configurations for quicker access to the latest data.
- **Data Batching**: A single reconfiguration across multiple objects to enhance efficiency.

Thank you!

For more information you can see the websites of our related projects:







